

PROGRAMMABLE LIMIT SWITCH



STANDARD FEATURES:

- INDIVIDUAL CHANNEL SPEED COMPENSATION
- 64 PROGRAMS (options to 512)
- 3 LEVELS OF PROGRAMMING ACCESS
- TIMED OUTPUTS
- MOTION DETECTION AND-ing
- SELECTABLE (2-1024) SCALE FACTOR (Resolver-based units)
- 12 VDC ACCESSORY POWER
- DUAL 3/4" BEARINGS IN ALL ENCODERS & RESOLVERS



OPTIONAL FEATURES:

- OUTPUT ENABLE MODES
- INDIVIDUAL LEADING AND TRAILING EDGE SPEED COMPENSATION
- SERIAL COMMUNICATION
- ANALOG OUTPUT
- GRAY CODE POSITION OUTPUT
- HIGH RESOLUTION (12-bit 4096)
- 220 VAC INPUT



OUTPUT GROUPING AND ENABLE MODES

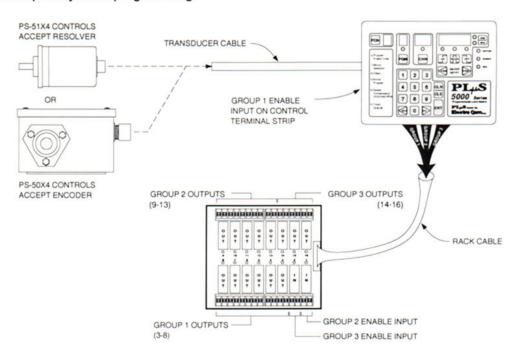
The PLuS 5XX4 controls have two features not found in other 5000 Series controls.

1. SUBDIVIDE OUTPUTS INTO GROUPS

The total I/O available on the I/O rack can be subdivided into groups. Each group can have a dedicated "Enable Input" as needed. The number of groups, number of outputs in each group and the number of "Enable Inputs" are established through simple keyboard programming.

2. OPERATE OUTPUT GROUPS IN DIFFERENT MODES

There are 4 modes of operation that each group can operate in. Incorporating these modes can reduce or eliminate the need for "hard wired" logic or interaction with PLCs.



The example illustration above shows a 16 I/O control with its outputs subdivided into 3 groups: group 1 = 6 outputs, Group 2 = 5 outputs, and Group 3 = 3 outputs. Each Group has a dedicated "Enable Input" and can be operated in one of

the 4 modes described in the following illustrations. The ability to have different modes of operation running simultaneously, within the same control, greatly increases application versatility, and reduces external hardware.

MODE 1

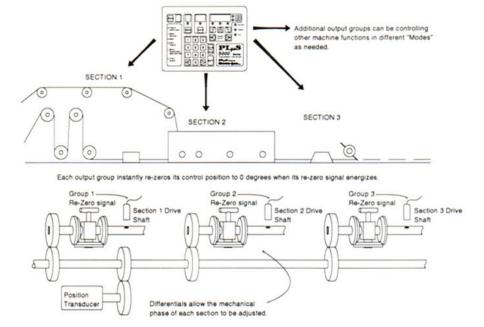
Control different sections of a machine that vary in mechanical phase relationship

This illustration shows a single PLµS control and position transducer controlling 3 "Adjustable Phase" sections of a converting machine.

The rotary position of the electrical output signals can be manually set/adjusted from PLµS keyboard or automatically adjusted by sensors. This keeps the electrical control signals properly synchronized to the mechanical devices in each section when phase adjustments are made.

1 position transducer provides position information for all sections of machine, regardless of their phase relationship.

NOTE: All gear drives are 1:1 ratio.



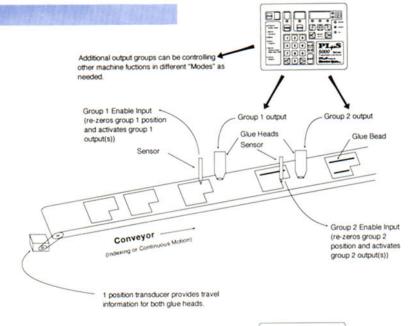
MODE 2

Control different machine functions asynchronously, on demand

This illustration shows a PLµS control and a single position transducer "independently" controlling 2 glue heads at different locations on a conveyor. The spacing between parts being glued is random.

Each output group instantly re-zeros its control position to 0 degrees when its enable input is energized. The outputs in the group then become active for up to 359 degrees.

Random spacing between parts is automatically handled because each enable sensor causes the position of its output group to re-zero. This references the output signals to the leading edge of the part being glued. When parts are not present the outputs will be inactive.

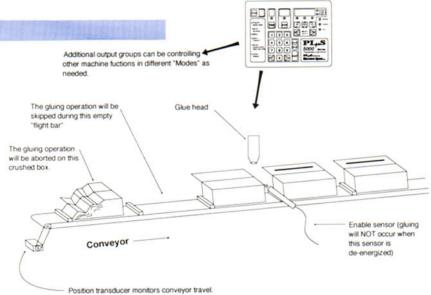


MODE 3

Operate a machine function only while a related input signal is maintained

In this illustration the glue head will only be allowed to operate while the photo eye sees the top edge of a box. Boxes that are not properly erected or crushed will cause the glue function to be aborted when the eye loses sight of the top edge.

Mode 3 operation eliminates the need to hardwire photo eyes and other sensors in series with the corresponding PL μ S control outputs. Instead, the sensor input is "ANDed" with the selected output(s) through simple programming.



MODE 4

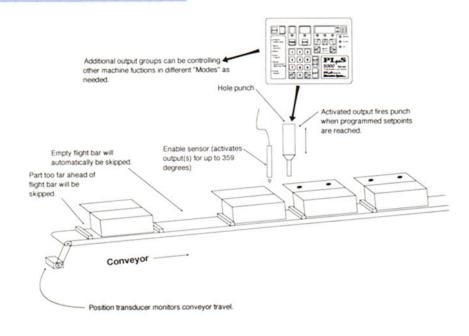
Operate machine function only if sensor detects part in correct position

In this illustration the punch will operate if the enable sensor detects the leading edge of the part at the correct position in the machine cycle.

The presence and correct position of parts is verified by the enable sensor before the output(s) are activated. The control position remains in sync with the machine position.

The output(s) in the group become active for up to 359 degrees IF the enable sensor signal occurs within a specified position in the machine cycle. Sensor signals that occur outside of the programmable "Enable Input Window" will be ignored.

This mode of operation is appropriate for flight bar conveyors, rotary index tables and similar types of machinery.



OUTPUT CONFIGURATIONS

PLµS Programmable Limit Switches are used in a wide variety of rotating shaft control applications:

- Switching machine devices ON and OFF directly (solenoid valves, clutch/brakes, etc.)
- Interfacing to other microprocessor-based control systems (such as Programmable Logic Controllers-PLC's)
- A combination of both of these configurations for direct output to "real time" critical functions (PLC scan delays can deteriorate high speed accuracy needed for some machine functions-gluing, registration control, etc.)

Each of these system configurations require specific components, and the PS-5000 Series is ideally suited because of the hardware options available. As shown below, the Keyboard/Controller is available in 3 basic output formats, each with distinct advantages. In addition, these Keyboard/Controllers are available in a NEMA 12 enclosure.

PS-5001, PS-5101, PS-5004, PS-5104 with separate Output Rack & Modules

These models use AC and/or DC Output Modules-suitable for directly switching machine devices, as well as PLC input. A system also includes an Output/Input Rack, Output Rack Cable and Output Modules (Input Modules on PS-5X04 Models, if used). Available in 16-, 24-, & 48-output models.



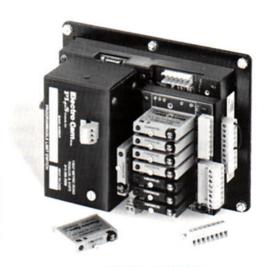
PS-5011, PS-5111 with built-in transistor outputs

These models provide 8 or 16 optically isolated DC sinking or sourcing outputs, each with 50 mA rating at 5-30 VDC. Output Rack, Cable, and Output Modules are not needed, signal wiring is direct to PLC or similar control logic circuitry. Uses pluggable terminal blocks on back of Keyboard/Controller.

PS-5021, PS-5121, PS-5024, PS-5124 with on-board AC and/or DC Output Modules

PS-5111-10-P16-C KEYBOARD/CONTROLLER

These models control up to 9 AC and/or DC Output Modules, mounted on back of Keyboard/Controller. The SLIMLINE Modules feature integral fuses and LED's. No separate output Rack or Cable is used; output wiring uses pluggable connectors on back of Keyboard/Controller. Fuse Tester circuit is provided on back of unit.



PS-5001-10-016 KEYBOARD/CONTROLLER W/PS-4100-11-016 RACK, CABLE & MODULES **PROGRAMMING FEATURES**

3 LEVELS OF PROGRAMMING ENABLE

The 3 program enable levels allow individuals to access control functions they need to adjust, while restricting access to other functions that go beyond that individual's responsibility.

"Master" enable level allows access to all functions and is used by engineering to initially configure the controller.

"Setup" enable level accesses all functions that could routinely need adjustment, but restricts access to functions that would normally be set once and not changed (Ex: Scale Factor, direction of forward rotation, etc).

"Operator" enable level allows only the setpoints and time values of specified output channels to be adjusted (these output channels are specified at "Master" level).

MOTION DETECTION AND-ing

Whenever the machine speed falls within the programmed High and Low RPM setpoints, the motion logic is in the ON state. Outputs can selectively by AND-ed with the motion logic so they will only be active when the machine speed is within RPM setpoints.

OFFSET

Full scale offset simplifies transducer installation.

24, 48 & 64 PROGRAMS

A program consists of all of the output setpoints and input enable setpoints needed to run a specific job. The control can store 64 of these programs (job setups) in permanent memory. 48 programs available in 24-output units; 24 programs available in 48-output units. Simply changing program numbers sets the control to run a different job.

INDIVIDUAL CHANNEL SPEED COMPENSATION

Speed compensation automatically advances the On/Off setpoints of an output channel proportional to machine speed to compensate for the response of the device being controlled. Each output channel can be speed compensated by a unique amount, regardless of how much speed compensation is needed for other outputs. Compensation is a linear function programmed in Degrees/1000RPM. Compensated output setpoints track machine speed changes. Optional LEADING & TRAILING EDGE SPEED COMPENSATION enables compensation of output devices which have different TURN ON/TURN OFF delays.

TIMED OUTPUTS

Output channels can selectively be programmed to turn ON at degree positions and turn OFF after a specified amount of time elapses. Timing resolution can be adjusted down to .2mSec increments. Also, a maximum OFF degree position can be programmed to turn OFF the output if that position is reached before the specified time has elapsed.

ACCESSORY POWER SUPPLY

Regulated 12VDC (150 mA max) power available for external devices.



SELECTABLE SCALE FACTOR (Resolver Models)

The resolver shaft position is decoded to 10 bit (1024 increments) resolution (Optional 12-bit resolution for 4096 increments), but the controller logic and display can operate at fewer increments per revolution if desired. For example, to display and program in degrees, a scale factor of 360 would be used (360 increments per revolution).

4 OUTPUT ENABLE MODES (PS-5XX4 Models)

Outputs can be subdivided into groups with dedicated enable signals. Each group can be assigned to operate in 1 of the following modes: (use of these modes can often eliminate the need for external logic)

MODE 1 - Outputs always active, switching ON and Off whenever programmed setpoints are reached. Enable signal causes degree position to reset to 0.

MODE 2 - Outputs are inactive until group enable signal occurs. Degree position then resets to 0 and outputs become active for up to 1 revolution.

MODE 3 - Outputs are only active while enable signal is ON. When enable signal is OFF, outputs will be inactive.

MODE 4 - Outputs are only active if enable signal occurs during specified window. The degree position for that group will not be changed and the outputs will become active for up to 1 revolution.

SERIAL COMMUNICATION (Optional) RS-232 & RS-422/485 PORTS

External communication devices can SEND and RECEIVE all program information within the PLµS control, either as individual setpoints and functions or as a complete memory upload or download. An Electro Cam software package is available for IBM compatible computers.

SYSTEM COMPONENTS

ORDERING INFORMATION

PS-5XXX-XX-XXX-X

ENCODER-BASED

(separate output rack)

PS-5001/5004 Keyboard/Controller Encoder Encoder Cable Output Rack Output Rack Cable Output Modules

Input Modules (PS-5004 Model)



RESOLVER-BASED (separate output rack)

PS-5101/5104 Keyboard/Controller Resolver Resolver Cable Output Rack

Output Rack Cable Output Modules Intput Modules (PS-5104 Model)



RESOLVER-BASED (Integral output rack)

PS-5111/5121*/5124* Keyboard/Controller Resolver Cable SLIMLINE Modules (PS-5121*/5124* Models)



ENCODER-BASED (Integral output rack)

PS-5011/5021*/5124* Keyboard/Controller Encoder Encoder Cable

SLIMLINE Modules (PS-5021*/5024* Models)



TRANSDUCER SELECTION

- 0 Encoder input 1 Resolver input

OUTPUT CONFIGURATION

- Separate Output Rack & Modules
 DC transistor outputs
- SLIMLINE modules* on
- Keyboard/Controller back

- Standard Features
- 4 Output enable modes & standard features

INPUT VOLTAGE

- 10 115VAC input 20 230VAC input

TYPE OF OUTPUT

- O Separate Rack & Output Modules

 M SLIMLINE Modules (PS. 572)
- SLIMLINE Modules (PS-5X2X Models)*
 DC Sinking output (PS-5X11 Models)
 DC Sourcing output (PS-5X11 Models)

NUMBER OF OUTPUTS

- 08 8 DC outputs (PS-5X11 Models) 09 9 SLIMLINE Modules (PS-5X2X Models)*
- 16 16 AC/DC Outputs 24 24 AC and/or DC Outputs 48 48 AC and/or DC Outputs

- A Analog output proportioned to RPM
- C Serial communication
- G Gray Code output
- H High resolution (12 bit-4096) Leading & trailing edge
- speed compensation

STANDARD OUTPUT MODULES

SLIMLINE OUTPUT MODULES*

PLµS Models, requiring output and input modules, use one of the following types of plug-in modules. An input or output module is required for each input or output being used. Module signals are isolated from one another, allowing AC and/or DC modules to be mixed on the same control, directly driving machine devices or interfacing to PLC's for logic functions. Slimline modules, used on PS-5X2X Models only, contain integral fuses and LED's for ease of monitoring and troubleshooting.

OUTPUT MODULES

DC Output: EC-ODC5 (Standard)

EC-ODC060-3 (Slimline)

0 to 60 VDC Output Voltage:

Input Voltage:

Input Voltage:

Input Current:

Output Current: 3 A @/below 35°C (95°F)

> Derate 35.7 mA/°C (19.8 mA/°F) 5 VDC nominal to 8 VDC maximum

DC Output: EC-ODC5A (Standard)

EC-ODC200-1 (Slimline)

0 to 200 VDC Output Voltage:

1 A @/below 45°C (113°F) Output Current: Derate 18 mA/°C (10 mA/°F)

5 VDC nominal to 8 VDC maximum

Input Voltage:

AC Output: EC-OAC5A-11 (Standard) EC-OAC240-3 (Slimline)

Load Voltage: 24 to 280 VAC rms

Load Current: 30 mA rms to 3 A rms @/below 35°C (95°F)

Derate 50 mA/°C (27.8 mA/°F)

Input Voltage: 5 VDC nominal to 8 VDC maximum Reed Relay: EC-ORR5 (Standard)

EC-ORR000-0 (Slimline) Output Type: N/O Reed Relay Contacts

10 VA maximum (DC resistive load) Contact Rating: 0 to 24 VDC/0 to 120 VAC rms Output Voltage:

Output Current: 100 mA DC maximum

30 mA AC maximum (resistive loads only)

Analog Output: EC-ANLG-010V (Standard)

EC-SANL-010V (Slimline) 12 Bits (4096 Increments)

Resolution:

0 to 10 VDC Output Voltage:

Output Current: 10 mA DC maximum Load Resistance: 1 K Ohm minimum

EC-ANLG-420M (Standard) **Analog Output:**

EC-SANL-420M (Slimline)

12 Bits (4096 Increments) Resolution:

Output Current: 4 to 20 mA DC Load Resistance: 450 Ohms maximum

INPUT MODULES

DC Input: EC-IDC5 (Standard) AC Input: EC-IAC5 (Standard)

EC-IDC032 (Slimline)

10 to 32 VDC Input Voltage:

25 mA maximum @ 32 VDC input

11 mA AC rms maximum Input Current: @ 140 VAC rms input Turn On Time: 20 ms typical

EC-IAC5A (Standard) AC Input:

EC-IAC240 (Slimline) 180 to 280 VAC

InputVoltage: Input Current: 5 mA AC rms maximum

@ 280 VDC rms input Turn On Time: 20 ms typical Turn Off Time: 20 ms typical

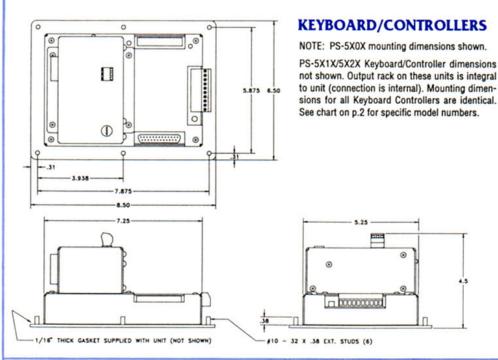
Turn On Time: 5 ms maximum Turn Off Time: 5 ms maximum

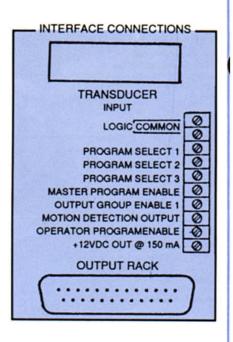
Turn Off Time:

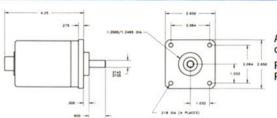
20 ms typical

EC-IAC120 (Slimline)

90 to 140 VAC rms



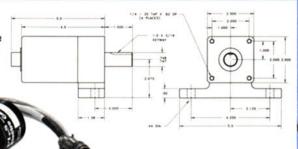




RESOLVERS

Alternate connector position available on side of resolver housing, specify:

PS-5238-11-ADS (flange-mount) PS-5275-11-ADS (foot-mount)



FOOT MOUNT

PS=5275-11-ADR

PS-4100-12-124 (24 Point)

FLANGE MOUNT PS-5238-11-ADR

RESOLVER CABLE

PS-5300-01- XXX

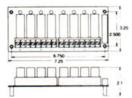


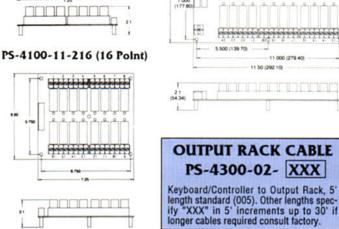
Keykboard/Controller to Resolver, 10' length standard (-010). Other lengths specify "-XXX" in 5' increments up to 30', 10' increments to 50', and 50' increments up to 1000'.

OUTPUT RACKS For use with PS-5X0X Controllers

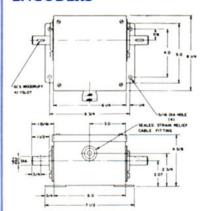
Order modules separately (p. 7), one module required per output. Output racks mounted with (4) #6 screws. Output Rack and Cable not used in PS-5X1X/5X2X systems (output rack integral to unit).

PS-4100-11-208 (8 Point)





ENCODERS



NEMA 12 Housing

PS-4256-11-DDR-(0 TO 1000 RPM) PS-4257-11-DDR-(0 TO 2000 RPM)

NEMA 4X Housing

PS-4456-11-DDR-(0 TO 1000 RPM) PS-4457-11-DDR-(0 TO 2000 RPM)



Note: NEMA 4x (stainless steel) not shown. Mounting dimensions are identical to NEMA 12 as shown.

ENCODER CABLE PS-4300-01- XXX Keyboard/Controller to Encoder, 10' length standard (010). Other lengths specify "XXX" in 5' increments up to 30' and 10' increments to 30'-200'.